CLAIM LISTING:

1. (Currently amended) A system for exerting a compressive force on an exterior treatment portion of a user's body comprising the user's thighs in synchrony with the heart beat of the user, comprising:

comprising a garment enclosing at least the user's thighs when worn by the user; and a plurality of electroactive polymer (EAP) actuators operably connected to the covering member, wherein said electroactive polymer actuators comprise an electroactive polymer member, a counter electrode and an electrolyte-containing region disposed between the electroactive polymer member and the counter electrode, wherein a plurality of said EAP actuators extend circumferentially around the user's thighs in multiple rows when worn by the user, wherein a plurality of actuators are provided in a spaced relationship in each single row, and wherein the spacings between EAP actuators in

a covering member for covering the treatment portion, said covering member

2. (Previously presented) The system of claim 1 wherein the EAP actuators are rigidly connected to the garment.

adjacent rows are offset longitudinally eircumferentially with respect to one another.

- 3. (Previously presented) The system of claim 2 wherein the EAP actuators are connected to the garment by adhesive.
- 4. (Previously presented) The system of claim 2 wherein the EAP actuators are stitched to the garment.
- 5. (Previously presented) The system of claim 2 wherein the EAP actuators are woven into the garment.
- 6. (Previously presented) The system of claim 1 and further comprising: a controller operably coupled to the EAP actuators to provide a drive signal to drive actuation of the EAP actuators.

- 7. (Previously presented) The system of claim 6 wherein the garment is flexible such that actuation of the EAP actuators drives deformation of the garment.
- 8. (Original) The system of claim 7 and further comprising: a heart sensor sensing a sinus rhythm of the heart and providing a heart sensor signal indicative of the sinus rhythm.
- 9. (Original) The system of claim 8 wherein the controller is configured to provide the drive signal based on the heart sensor signal.
- 10. (Original) The system of claim 9 and further comprising: a feedback component sensing a feedback characteristic and providing a feedback signal indicative of the sensed feedback characteristic.
- 11. (Original) The system of claim 10 wherein the controller is configured to provide the drive signal based on the feedback signal.
- 12. (Original) The system of claim 11 wherein the feedback component comprises: a metabolic sensor sensing a metabolic characteristic and providing the feedback signal based on the metabolic characteristic.
- 13. (Original) The system of claim 11 wherein the feedback component comprises: a blood flow sensor.
- 14. (Original) The system of claim 11 wherein the feedback component comprises: a blood pressure sensor.
- 15. (Cancelled)
- 16. (Original) The system of claim 6 wherein the controller is configured to provide the drive signal to exert counterpulsation force on the treatment portion.

17. (Cancelled)

18. (Currently amended) A counterpulsation apparatus, comprising: a garment enclosing at least the thighs of a user when worn by the user; and a plurality of electroactive polymer (EAP) actuators connected to the garment, wherein said electroactive polymer actuators comprise an electroactive polymer member, a counter electrode and an electrolyte-containing region disposed between the electroactive polymer member and the counter electrode, wherein a plurality of said EAP actuators extend circumferentially around the user's thighs in multiple rows when worn by the user, wherein a plurality of actuators are provided in a spaced relationship in each single row, and wherein the spacings between EAP actuators in adjacent rows are offset eircumferentially longitudinally with respect to one another.

19. (Cancelled)

- 20. (Previously presented) The counterpulsation apparatus of claim 18 wherein the garment is formed of a fabric material.
- 21. (Original) The counterpulsation apparatus of claim 20 wherein the plurality of EAP actuators are woven into the fabric material.
- 22. (Original) The counterpulsation apparatus of claim 20 wherein the plurality of EAP actuators are stitched to the fabric material.
- 23. (Original) The counterpulsation apparatus of claim 20 wherein the plurality of EAP actuators are connected to the fabric material with adhesive.
- 24. (Previously presented) The counterpulsation apparatus of claim 18wherein the garment comprises multiple layers of fabric material and wherein the plurality of EAP actuators are disposed between the layers.

- 25. (Currently amended) A method of exerting pressure on an external-treatment area of a patient comprising the patient's thighs, comprising: providing a garment to cover the treatment area; and actuating electroactive polymer (EAP) actuators connected to the garment in synchrony with the heart beat of the user patient, wherein said electroactive polymer actuators comprise an electroactive polymer member, a counter electrode and an electrolyte-containing region disposed between the electroactive polymer member and the counter electrode, wherein a plurality of said EAP actuators extend circumferentially around the user's patient's thighs in multiple rows, wherein a plurality of actuators are provided in a spaced relationship in each single row, and wherein the spacings between EAP actuators in adjacent rows are offset longitudinally circumferentially with respect to one another.
- 26. (Original) The method of claim 25 and further comprising: sensing a heart beat of the patient and providing a heart beat sensor signal indicative of the sensed heart beat.
- 27. (Original) The method of claim 26 and further comprising: actuating the EAP actuators to exert counterpulsation pressure based on the heart beat sensor signal.
- 28. (Original) The method of claim 27 and further comprising: sensing a biological characteristic indicative of an efficaciousness of the counterpulsation pressure and providing a biological sensor signal indicative of the sensed characteristic.
- 29. (Original) The method of claim 28 wherein actuating the EAP actuators comprises: actuating the EAP actuators based on the biological sensor signal.
- 30. (Previously presented) The system of claim 1, wherein the electroactive polymer actuator comprises a conducting polymer.

- 31. (Previously presented) The system of claim 1, wherein the electroactive polymer actuator comprises a conducting polymer selected from polyaniline, polypyrrole, polysulfone, polyacetylene and combinations thereof.
- 32. (Previously presented) The counterpulsation apparatus of claim 18, wherein the electroactive polymer actuator comprises a conducting polymer.
- 33. (Previously presented) The counterpulsation apparatus of claim 18, wherein the electroactive polymer actuator comprises a conducting polymer selected from polyaniline, polypyrrole, polysulfone, polyacetylene and combinations thereof.
- 34. (Previously presented) The method of claim 25, wherein the electroactive polymer actuators comprise a conducting polymer.
- 35. (Previously presented) The method of claim 25, wherein the electroactive polymer actuators comprise a conducting polymer selected from polyaniline, polypyrrole, polysulfone, polyacetylene and combinations thereof.